

Future Technology Devices International Ltd.

Application Note AN_118

**Migrating Vinculum Designs From
VNC1L to VNC2-48L1A**

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The purpose of this document is to provide guidelines for migrating VNC1L designs to VNC2.

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1 Introduction

The Vinculum VNC2 is FTDI's 2nd generation USB host controller solution and it expands on the capabilities of the VNC1L. VNC2 is supplied in 6 different packages. These are 32 pin QFN and LQFP packages, 48 pin QFN and LQFP packages and 64 pin QFN and LQFP packages.

The smaller packages reduce the number of IO by 16 pins to allow for more compact designs where space limitations are a consideration.

The larger packages provide additional 16 I/O to allow for increased functionality. In addition to the increased number of VNC2 package options, there is also a new software development tool suite developed by FTDI to enable users to create their own customised firmware.

The main focus of this document will be on how to migrate from a design using the VNC1L to a VNC2-48L1A device.

2 VNC1L vs VNC2

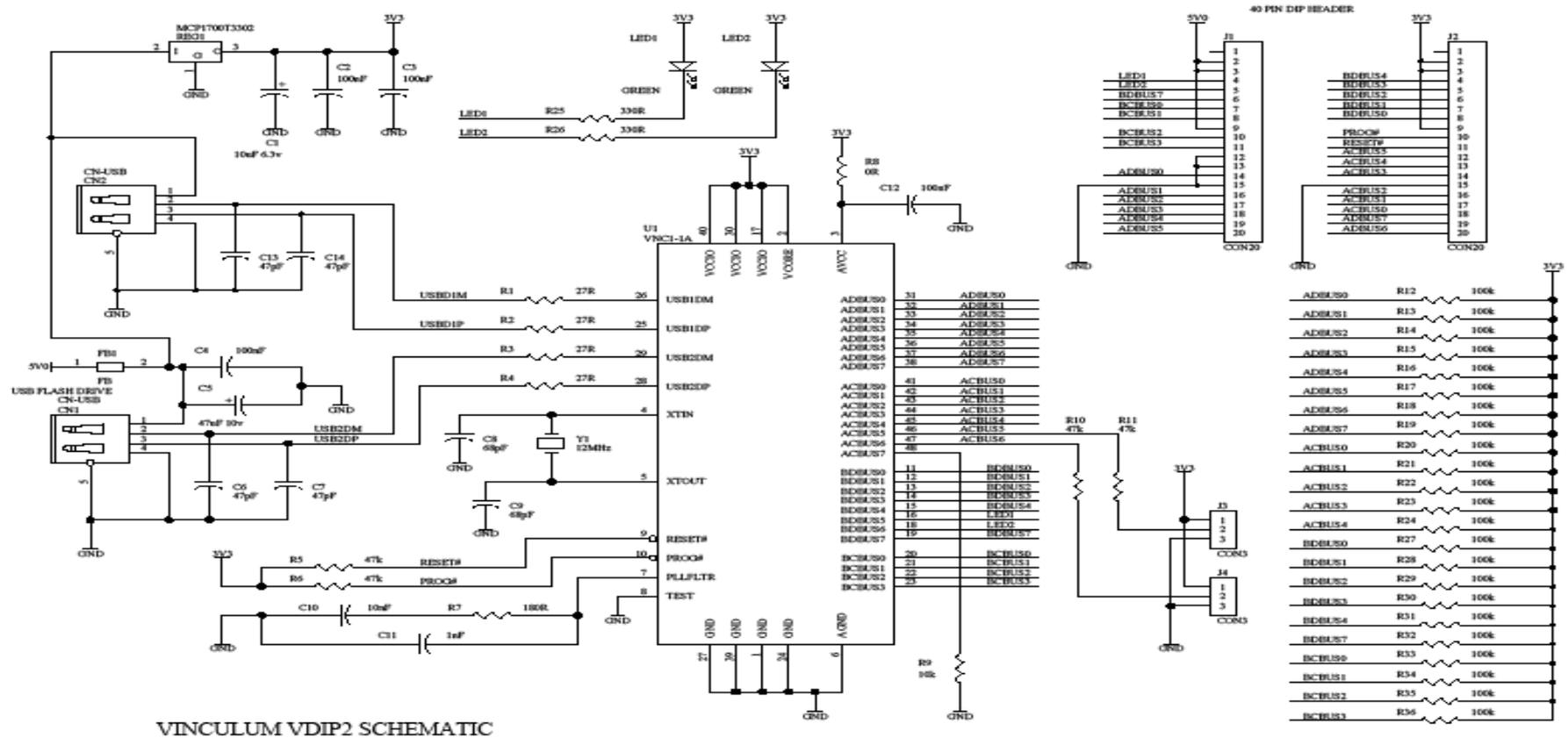
The main features of the two generations of devices are shown below. All features are available in the 64 pin packages. The 48 pin and 32 pin packages have the same memory and internal functions but less I/O. The 48 pin package matches the VNC1L device. For full details see the VNC2 Datasheet at www.ftdichip.com

FEATURE	VNC1L	VNC2
MECHANICAL		
Package	48 pin LQFP	64, 48,32 pin QFN or LQFP
Temperature	-40 to +85C	-40 to +85C
ELECTRICAL		
VCC	3V3	3V3
VCCIO	5V tolerant 3V3	5V tolerant 3V3
CLK source	12MHz (external)	12MHz (external)
CPU		
	8-bit Harvard architecture	16-bit Harvard architecture
INTERFACING		
USB ports	2	2
UART port	1	1
SPI slave port	1	2
SPI master port	0	1
FIFO monitor port option	1	1
Debug port	0	1
FIRMWARE		
Precompiled firmware	YES	YES
Tools for creating own firmware	NO	YES
MEMORY		
DATA RAM	4k x 8 (4kbytes)	4k x 32 (16kbytes)
E-FLASH	64k x 8 (64kbytes)	128k x 16 (256kByte)
USB MODES		
Speed	Full / low	Full / low
Transfer modes	Bulk / Interrupt	Bulk, interrupt, isochronous
CONFIGURATION PORTS		
UART	YES	YES
USB	YES (after initial programming)	YES
SPI	NO	YES
FIFO	NO	YES
DEBUG PORT	N/A	YES

3 Reference Schematics

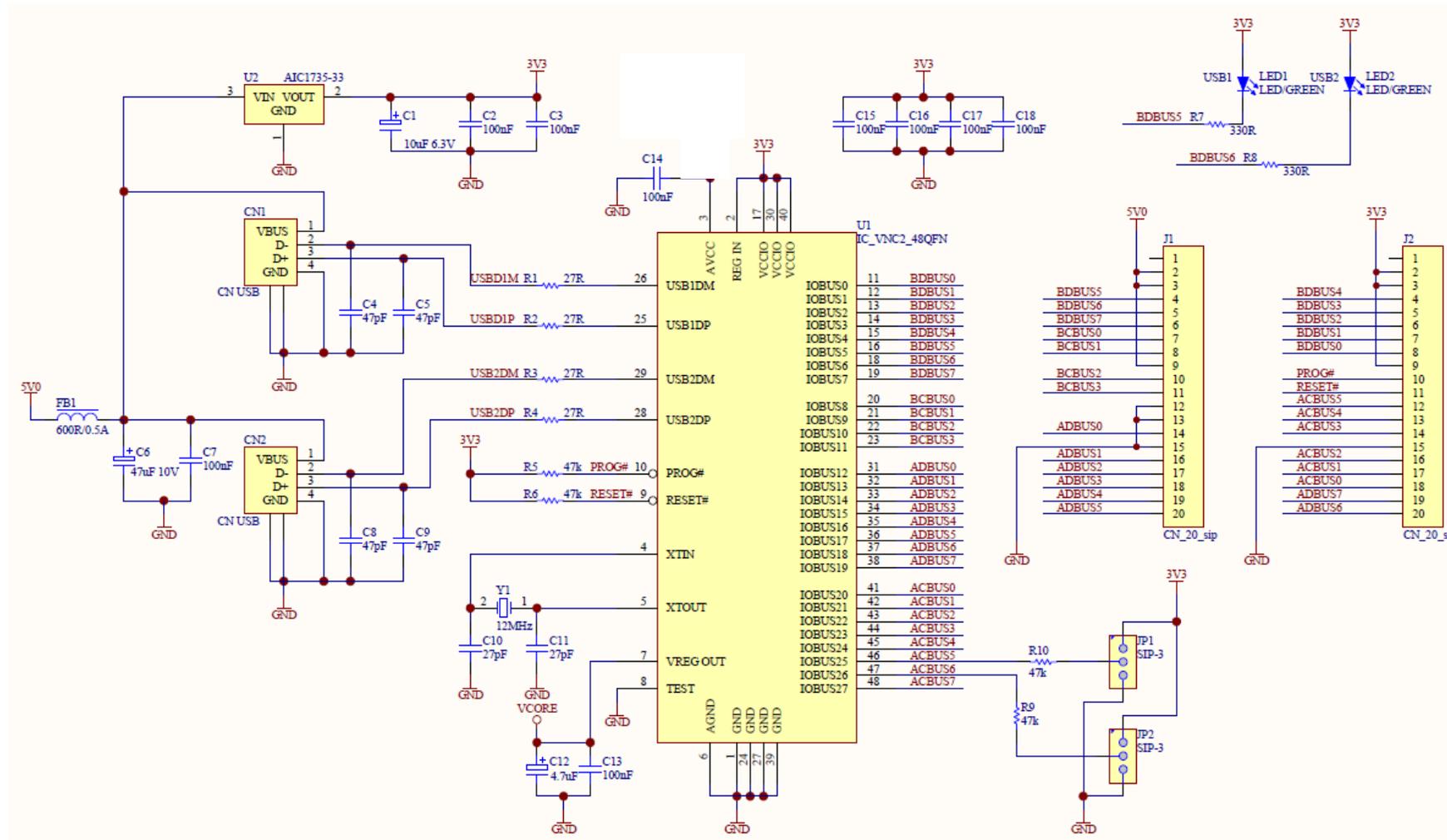
3.1 VNC1L schematic

This schematic is for the VDIP2 based on the VNC1L.



VINCULUM VDIP2 SCHEMATIC

3.2 VNC2-48L1A Equivalent of VNC1L VDIP2 Reference Schematic



4 BOM Change required to convert from VNC1L to VNC2-48L1A

VNC1L Schematic Component	VNC2-48L1A Schematic Component	Description
U1 - VNC1L	U1 -VNC2-48L1A	Controller IC
C8, C9 – 68pF Capacitor	C10, C11 – 27pF Capacitor	Load capacitor on crystal
R9, 10k resistor	Do not fit pull down on U1 pin 48	PLL enable
R7, 180R	Replace with 0R link or simply track over if redesigning PCB	VNC1L PLL Filter / VNC2 VREGOUT
C10, 10nF	C12, 4.7uF	VNC1L PLL Filter / VNC2 VREGOUT
C11, 1nF	C13, 100nF	VNC1L PLL Filter / VNC2 VREGOUT
R8, 0R to 3V3		Remove

The pull up resistors, shown on the VNC1L schematic R12-R36, are optional even on the VNC1L schematic.

Pin 3 AVCC of the VNC2-48L is internally bonded to the 1V8 internal regulator. This is the only package with this internal bond for ease of upgrade from a VNC1L.

5 Firmware

As the internals of the two devices is different, the firmware that runs on the devices is different. However to maintain backward compatibility there is equivalent firmware available for download.

VNC1L Firmware	VNC2 Firmware
VDAP	V2DAP
VMSC	V2MSC
VDPS	V2DPS
VCDC	V2CDC
VDIF	V2DIF2

These builds may be downloaded from www.ftdichip.com (at the time of writing this application note, some of these builds were not available, but were scheduled to be put onto the website soon).

In addition to using these pre-compiled libraries, VNC2 is supplied with a software development tool chain to allow customers to customise the pre-compiled firmware or create their own firmware for greater flexibility in design.

Note: The precompiled builds are designed for the 48 pin pkg as that was all VNC1L was available in.

6 Loading Firmware

VNC1L was limited to using the UART to load firmware onto a blank device. The VNC2 may be programmed via the debug port or via the UART interface. Although FTDI will provide utilities for this, there may be situations where users prefer to develop their own programmer over the UART and there are some significant differences between VNC1L and VNC2.

Key differences between VNC1L and VNC2:

- Each block of the flash on the VNC2 is 128 bytes compared with 64 bytes on the VNC1L.
- The endianness of the VNC2 is different from that of the VNC1L meaning that data must be reversed before it can be sent to the device.
- The size of the ROM files on VNC1L were all 64k, the ROM files on the VNC2 can be anything up to the size of the flash.

To program the VNC2 firmware over the UART the device must be reset in prog mode; this is achieved by driving the **prog#** pin low and then driving the **reset#** pin low then high. When the device is in prog mode it is ready to be programmed over the UART using the following command / response standard.

Command Name	Command(s):	Response	Comment
Echo	0xFF	0xFF	
Echo	0xFB	0xFB	VNC1L used the 0xFA command to echo, VNC2 uses 0xFB to distinguish between the devices.
Set Baud Rate	0x01 BaudRate(1, 2 or 3)	0x02	(115200 Baud == 1, 1 MBaud == 2, 3 MBaud == 3)
Read Address	0x02 FlashAddrLow FlashAddrHigh	0x02 Data to Read	
Write Address	0x03 FlashAddrLow FlashAddrHigh Data to Write	0x02	The 0x02 response will be sent after FlashAddrHigh has been received by the device.

Below is a snippet of the test code that has been used to write and verify the flash of the VNC2....

```
// Sample code for writing flash of VNC2 written in C/C++.

// Function: sendData - writes the data read from the ROM file to the VNC2 and verifies it.
// Parameters: romfile - a handle to the ROM file obtained from the open(...) function.
//             filename - a char array containing the name of the rom file that we have opened.
//             ftHandle - handle to the TTL cable that we are communicating over.
// Return:      returns 1 on successful completion, !1 otherwise.

char sendData(int romfile, char *filename, FT_HANDLE ftHandle)
{
    unsigned long filesize;
    unsigned long pageSegCount;           // The amount of pages needed to store the ROM file.
    unsigned long pageRem = 0;           // Portion of a ROM file left over that doesn't fill a full
                                        // page.
    unsigned long numwrit;               // Not required to be used....
    unsigned long padByteCnt = 0;
    unsigned long padSegRem = 0;
    unsigned long padSegSize = (1 * 128);
    unsigned char databuf[PAGESIZE];    // Data read from the ROM file.
```

```
unsigned char endianBuf[PAGESIZE]; // Data read from the ROM file reversed to accommodate
// VNC2 endianness
unsigned char receiveBuf[PAGESIZE]; // Data received from the VNC2
unsigned char j = 0;
unsigned char cmd;
unsigned char dataread = 0x00;
unsigned char baudbuf[6];
FT_STATUS ftStatus;
unsigned long i; // Index used as the location within the device flash.

struct stat stbuf;
stat(filename, &stbuf);

// FILE SIZE CALCULATIONS
filesize = stbuf.st_size;
pageSegCount = filesize / PAGESIZE;
pageRem = filesize % PAGESIZE;

//echo from the device...
cmd = 0xFF;
ftStatus = FT_Write(ftHandle, &cmd, 1, &numwrit);
numwrit = 0;
ftStatus = FT_Read(ftHandle, &dataread, 1, &numwrit);

cmd = 0xFB;
ftStatus = FT_Write(ftHandle, &cmd, 1, &numwrit);
numwrit = 0;
ftStatus = FT_Read(ftHandle, &dataread, 1, &numwrit);

// Set the baud rate of the chip...
cmd = 0x01;
baudbuf[0] = cmd;
baudbuf[1] = 0x03; // 1, 2 or 3

ftStatus = FT_Write(ftHandle, baudbuf, 2, &numwrit);

// Allow some time for the baud rate to settle...
Sleep(100);

// Set the baud rate of the TTL cable.
FT_SetBaudRate(ftHandle, 3000000);

numwrit = 0;
ftStatus = FT_Read(ftHandle, &dataread, 1, &numwrit);
if(dataread != 0x02)
{
    printf("The baud rates aren't synced, exiting.\n");
    return -1;
}

//echo from the device...
cmd = 0xFB;
FT_Write(ftHandle, &cmd, 1, &numwrit);
numwrit = 0;
FT_Read(ftHandle, &dataread, 1, &numwrit);

cmd = 0xFF;
FT_Write(ftHandle, &cmd, 1, &numwrit);
numwrit = 0;
FT_Read(ftHandle, &dataread, 1, &numwrit);

printf("Writing File");

// Increment by one to accommodate the fractional page, the fractional page will be memset with
// 0xFF...
```

```
pageSegCount++;

for(i = 0; i < pageSegCount; i++)
{
    unsigned char transdata[2];
    int numread = 0;

    // Memset the data buffer...
    memset(databuf, 0xFF, PAGESIZE);

    numread = read(romfile, databuf, PAGESIZE);

    // Change the data to little? endian for VNC2.
    for (j=0; j < PAGESIZE; j += 2)
    {
        endianBuf[j] = databuf[j+1];
        endianBuf[j+1] = databuf[j];
    }
/*
    WRITE FORMAT
    0x03
    FlashAddressLow
    FlashAddressHigh
    Data block to write.
*/
    cmd = 0x03;
    FT_Write(ftHandle, &cmd, 1, &numwrit);

    transdata[0] = (i & 0xFF);
    transdata[1] = ((i >> 8) & 0xFF);

    // Send the data address....
    FT_Write(ftHandle, transdata, 2, &numwrit);

    // Check for a response from this....
    FT_Read(ftHandle, &dataread, 1, &numwrit);
    if(dataread != 0x02)
    {
        printf("!");
        return -1;
    }

    // Send the data.
    // Send the data address....
    FT_Write(ftHandle, endianBuf, PAGESIZE, &numwrit);

    // Check for a response again....
    FT_Read(ftHandle, &dataread, 1, &numwrit);
    if(dataread == 0x02)
    {
        printf(".");
    }
    else
    {
        printf("!");
        return -1;
    }
}

/*
    READ FORMAT
    0x02
    FlashAddressLow
    FlashAddressHigh
*/
// Read the data back to make sure that it has been programmed correctly.
```

```
cmd = 0x02;
transdata[0] = (i & 0xFF);
transdata[1] = ((i >> 8) & 0xFF);

// Send the command
FT_Write(ftHandle, &cmd, 1, &numwrit);

// Send the data address...
FT_Write(ftHandle, transdata, 2, &numwrit);

// Check for a response from this...
FT_Read(ftHandle, &dataread, 1, &numwrit);
Sleep(10);

// Make sure that we have 128 bytes to read from the chip!!!
FT_GetQueueStatus(ftHandle, &numwrit);
if(numwrit < PAGESIZE)
{
    printf("Not enough data to read");
    return -1;
}

// Read 128 bytes back from the chip...
FT_Read(ftHandle, receiveBuf, PAGESIZE, &numwrit);

// Compare the data read back from the flash with the data sent...
// NOTE: The data that is returned is reversed due to the endianness of the VNC2,
// compare the returned data with the data that we reversed to send to the chip.
for(j = 0 ; j < PAGESIZE; j++)
{
    if(endianBuf[j] != receiveBuf[j])
    {
        printf("The data returned is not the same!");
        return -1;
    }
}
return 1;
}
```

7 Summary

In summary VNC2 will allow for existing PCBs to be upgraded to the more powerful device without needing to change the PCB, but will also allow for greater customisation of the firmware and hence a better product and user experience.

New designs, requiring new PCBs may also opt for different device packages.

The 32 pin option will allow for smaller designs where space is a consideration.

The 64 pin package will allow for additional functionality to be added via the extra pin count.

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Appendix A – SPI Clarification

There is a subtle difference in the SPI mode of operation between VNC1L and VNC2 in VNC1L SPI backward compatible mode.

In essence VNC1L waits for the chip select line to go active and then the start bit must be a '1' for the transaction to begin.

In VNC2 backward compatibility mode the chip waits for the chip select to go active and then counts the next 12 clocks as the full transmission. The start bit is effectively a don't care state.

If the SPI interface is accessed by the external controller (master) by bit-banging the SPI bits of the interface there will be no new problems.

If the SPI interface is accessed by the external controller using its in-built 8-bit wide SPI interface and simply padding with 0's either at the front or the end of the message it will not work.

As such the interface must be bit-banged to ensure it works with VNC1L and VNC2 in this mode. The first bit after the chip select is active must be the start bit. No padding is allowed.

Appendix B – Revision History

Version Preliminary	First Preliminary version available	1 st Feb 2010
Version 1.0	First release Rev 1.0 available	19 th Feb 2010
Version 1.1	Added new chapter 6 for loading firmware over UART	22 nd March 2010
Version 1.2	Modified chapter 6	22 nd April 2010
Version 1.3	Correction to write opcode in section 6 Added appendix A	13 th May 2011